

# Randomised Algorithms: Linear Programming and Approximation Algorithms

February 2023

## 1 LPs and Simplex

**Exercise 1** Convert the following LP into slack form. Also state the set of basic and non-basic variables.

$$\begin{array}{rllllll} \text{maximise} & 2x_1 & & - & 6x_3 & & \\ \text{subject to} & & & & & & \\ & x_1 & + & x_2 & - & x_3 & \leq 7 \\ & 3x_1 & - & x_2 & & & \geq 8 \\ & -x_1 & + & 2x_2 & + & 2x_3 & \geq 0 \\ & & & & & x_1, x_2, x_3 & \geq 0 \end{array}$$

[Source: CLRS: 29.1-5]

**Exercise 2** Show that the following LP is infeasible:

$$\begin{array}{rllllll} \text{maximise} & 3x_1 & - & 2x_2 & & & \\ \text{subject to} & & & & & & \\ & x_1 & + & x_2 & \leq & 2 & \\ & -2x_1 & - & 2x_2 & \leq & -10 & \\ & & & x_1, x_2 & \geq & 0 & \end{array}$$

[Source: CLRS: 29.1-6]

**Exercise 3** Show that the following LP is unbounded:

$$\begin{array}{rllllll} \text{maximise} & x_1 & - & x_2 & & & \\ \text{subject to} & & & & & & \\ & -2x_1 & + & x_2 & \leq & -1 & \\ & -x_1 & - & 2x_2 & \leq & -2 & \\ & & & x_1, x_2 & \geq & 0 & \end{array}$$

[Source: CLRS: 29.1-7]

**Exercise 4** Find a linear program which has more than one optimal solution.

**Exercise 5** Solve the following linear program using SIMPLEX:

$$\begin{array}{rllllll} \text{maximise} & 5x_1 & - & 3x_2 & & & \\ \text{subject to} & & & & & & \\ & x_1 & - & x_2 & \leq & 1 & \\ & 2x_1 & + & x_2 & \leq & 2 & \\ & & & x_1, x_2 & \geq & 0 & \end{array}$$

[Source: CLRS: 29.3-6]

**Exercise 6** Solve the following linear program using SIMPLEX:

$$\begin{array}{rllll} \text{maximise} & x_1 & + & 3x_2 & \\ \text{subject to} & & & & \\ & x_1 & - & x_2 & \leq 1 \\ & 2x_1 & + & x_2 & \leq 2 \\ & x_1, x_2 & & & \geq 0 \end{array}$$

[Source: CLRS: 29.3-6]

**Exercise 7** Attempt [2015P7Q2](a)-(b).

**Exercise 8** Attempt [2018P27Q1](a)-(b).

**Exercise 9 [Duality]** Attempt [2018P27Q1](c).

**Exercise 10** Attempt [2019P8Q1].

**Exercise 11** Attempt [2020P8Q1](a).

## 2 Formulating problems as Linear Programs

**Exercise 12 [Shortest path]** Consider the linear program for the shortest path problem from  $s$  to  $t$ .

1. What happens if there is a negative-weight cycle?
2. Prove that, if there are no negative-weight cycles, the optimal solution  $\bar{d}_t$  of the linear program equals the correct distance  $d_t$ .
3. How would you formulate the single-source shortest path problem as a linear program?

**Exercise 13 [Multi-commodity flow]** In the *multi-commodity flow* problem, there is a graph  $G = (V, E)$  where edges have capacities  $c(u, v)$ . There are  $k$  commodities  $K_1, \dots, K_k$ , where  $K_i = (s_i, t_i, d_i)$ , meaning that there is a demand of  $d_i$  from source  $s_i$  to destination  $t_i$ . Formulate this as a linear program (LP).

**Exercise 14 [Minimum Spanning Tree]**

- (a) Formulate the (undirected) Minimum Spanning Tree problem as an integer program (possibly using an exponential number of constraints).

*Hint: Think about subtour eliminations.*

- (b) Formulate the linear relaxation of the integer program.
- (c) Show that given a fractional solution to the linear relaxation, there is a polynomial time algorithm to convert the fractional solution into an integer one with the same cost. What does this show?

(Answer)

- (a) Let  $x_{uv} \in \{0, 1\}$  indicate whether the edge  $(u, v)$  is in the output MST. Then the cost of the MST is  $\sum_{uv \in E} x_{uv} w_{uv}$ . We need to add constraints so that the indicators do not form a cycle. This means that every set of vertices  $S \subseteq V$  must have at most  $|S| - 1$  internal edges:

$$\sum_{(u,v) \in E(S,S)} x_{uv} \leq |S| - 1.$$

Hence, putting it all together, we have that:

$$\begin{aligned} & \text{maximise} && \sum_{uv \in E} x_{uv} w_{uv} \\ & \text{subject to} && \\ & && x_{uv} \in \{0, 1\} \quad \forall uv \in E \\ & && \sum_{uv \in E} x_{uv} = |V| - 1 \\ & && \sum_{(u,v) \in E(S,S)} x_{uv} \leq |S| - 1 \quad \forall \emptyset \subset S \subseteq V \end{aligned}$$

- (b) If all values  $x_{uv}$  are integer then it means that the induced solution is indeed a spanning tree and it indeed has the minimum value.

Otherwise, a cycle is formed and this cycle must have one edge  $e$  with  $x_e < 1$ . By picking the heaviest edge  $e'$  on the cycle and moving as much of  $x_{e'}$  to  $x_e$  making one of the two either 0 or 1, we obtain a solution with one integer solution value and the same (or smaller) cost.

*Note:* If the edge weights are unique, then the MST is unique and we can argue about integrality since there can be no cycle.

**Exercise 15 [Min-Cost Bipartite Matching]** In the *min-cost bipartite matching* problem, we are given a bipartite graph  $G = (X \cup Y, E)$  with  $|X| = |Y|$  and a weight function  $w : X \times Y \rightarrow \mathbb{R}$  and our goal is to find the bipartite matching with the minimum cost.

- Formulate this as an integer program.
- Formulate the linear relaxation of the integer program.
- (+) Give a polynomial-time algorithm for converting a fractional solution of the linear relaxation to a solution to the original problem.

*Hint:* Given a fractional solution, modify the solution so that the number of integral values (0 or 1) in the solution increases, and the objective remains the same.

**Exercise 16 [Bounded Degree MST]** Formulate as an integer program the bounded degree MST problem, where we want to find the MST where each vertex has at most  $d$  neighbours.

**Exercise 17** Attempt [2017P7Q1](a)-(b).

**Exercise 18** Attempt [2020P8Q1](c).

**Exercise 19** Prove that the LP formulation of the SET-COVER problem (Lecture 10, slide 4) is feasible if and only if the SET-COVER instance has a feasible solution.

### 3 Convex sets

**Extended Note 1 [Convex set]** Recall a set  $S$  is **convex** if for every  $x, y \in S$ ,  $\lambda x + (1 - \lambda)y \in S$  for all  $\lambda \in [0, 1]$ .

**Exercise 20**

- Show that the intersection of two convex sets  $C_1$  and  $C_2$  are convex.
- Show that the union of two convex sets need not be convex.

**Exercise 21**

- Prove that for any  $a_1, \dots, a_n, b \in \mathbb{R}$ , we have that the set

$$\mathcal{A} := \{x \in \mathbb{R}^n : a_1 x_1 + \dots + a_n x_n \leq b\}$$

is convex.

(b) Prove that the set of feasible solutions of a linear program forms a convex set.

## 4 (non-randomised) approximation algorithms

### Exercise 22 [Vertex Cover]

- (a) Analyse the greedy algorithm for the unweighted Vertex cover problem that achieves an approximation ratio of 2 (Slide 14 of Lecture 9).
- (b) **Bonus-Question:** What is the problem behind the “more natural” greedy approach where instead of both endpoints of an uncovered edge, we only include one of the two endpoints into our cover?

**Exercise 23 [Minimum Cardinality Maximal Matching]** Design a factor 2 approximation algorithm for the problem of finding a minimum cardinality maximal matching in an undirected graph. A matching is *maximal* if no other edge can be added to the matching.

*Hint: Use the fact that any maximal matching is at least half the maximum matching.*

**Exercise 24 [Maximum acyclic graph]** Given a directed graph  $G = (V, E)$ , pick a maximum cardinality set of edges from  $E$  so that the resulting subgraph is acyclic. Design an approximation algorithm for this problem.

(Answer) Consider the following algorithm:

1. Arbitrarily number of the vertices of the graph.
2. Let  $F$  be the set of edges  $(u, v)$  with  $u < v$  and  $B$  the set of edges  $(u, v)$  with  $v < u$ .
3. Return the largest of the two sets  $B$  and  $F$ .

It is clear that both edge sets induce an acyclic graph. The two sets satisfy  $|B| + |F| = |E|$  and so one of the two must have size at least  $|E|/2$ . Since the optimal answer may have at most  $|E|$  edges, this proves an approximation ratio of 2.

**Exercise 25 [Next-Fit for Bin-Packing]** Consider the Next-Fit heuristic for the bin-packing problem. Show that it is a 2-approximation algorithm.

**Exercise 26 Attempt [2017P9Q1].**

**Exercise 27 [Metric TSP]** Consider TSP problem on a graph  $G = (V, E)$  with cost function  $c : V \times V \rightarrow \mathbb{R}$ , which satisfies  $c(u, v) + c(v, w) \geq c(u, w)$  for all  $u, v, w \in V$ . Consider the algorithm that picks an arbitrary root  $r$  and then finds an MST from that root, and as a solution returns a walk of the MST (e.g. the pre-order traversal). Show that this algorithm achieves a 2-approximation for this version of the TSP.

(Answer) See these old slides.

**Exercise 28 Attempt [2015P7Q2](c).** *Hint: First look at Exercise 27.*

**Exercise 29 [Christophides' algorithm] (+)** Read about Christophides' algorithm for the TSP problem from these slides. Show that it achieves a  $3/2$ -approximation ratio.

**Exercise 30 Attempt [2018P9Q1].**

**Exercise 31** Consider an instance of the unweighted SET-COVER problem with the condition that no element  $x \in X$  appears in more than  $k$  many subsets. Design an approximation algorithm based on deterministic rounding which achieves an approximation ratio of at most  $\mathcal{O}(k)$ .

## 5 Randomised approximation algorithms

**Exercise 32** Consider a MAX-SAT formula where each clause has at least 4 literals. Design a randomised approximation algorithm and analyse its approximation ratio.

**Exercise 33 [MAX-4-CNF]** Attempt [2016P9Q1](b).

**Exercise 34** Consider the randomised approximation algorithm for the weighted SET-COVER problem. Translate the algorithm from the course into one based on non-linear randomised rounding such that, given the LP solution  $y$ , we directly round this LP solution to get a cover  $C$  which (i) covers all elements with probability  $1 - 1/n$ , and (ii) has an expected cost which is at most  $\mathcal{O}(\log n)$  times the cost of the optimal cover.

*Hint: By non-linear we refer to the way of choosing the probability of setting a variable to 1. The randomised rounding rules in the lecture is linear in the sense that the probability is equal to the fractional value of the LP solution.*

**Exercise 35** Attempt [2017P7Q1](c).

**Exercise 36** Attempt [2020P9Q1].

**Exercise 37** Recall the randomised algorithm for SET-COVER presented in the lecture. As input, we have a SET-COVER instance with  $n$  elements; and let us additionally assume we have at most  $\text{poly}(n)$  many subsets (and also that we can cover all  $n$  elements, i.e.,  $\bigcup_{s \in \mathcal{F}} S = X$ ). The algorithm achieves with probability  $1/3$  that the returned cover is correct and the cost of the cover is at most a factor of  $4 \ln(n)$  away from the optimal cost (see Lecture 10, slide 9.2). Turn this into a randomised algorithm such that:

1. The algorithm terminates in a time that is polynomial in the input size, with probability 1 (i.e., always).
2. The algorithm returns a correct solution, with probability 1 (i.e., always).
3. The expected approximation ratio is  $\mathcal{O}(\log n)$ .