

# Model Answers Complexity Theory

tms41, dl516

last updated: 16.5.2023, 22:22

**Question** (Exercise Sheet 1, Question 1). *In the lecture, a proof was sketched showing a  $\Omega(n \log n)$  lower bound on the complexity of the sorting problem. It was also stated that a similar analysis could be used to establish the same bound for the Travelling Salesman Problem. Give a detailed sketch of such an argument. Can you think of a way to improve the lower bound?*

*Answer.* The computation tree with branches, binary decisions and  $n!$  leaves is the same as with sorting. Also the derivation why  $\log(n!) = \Theta(n \log n)$  can be found in the lecture notes of Complexity Theory [page 5]. What remains to be verified that indeed all  $n!$  leaves are needed. Each leaf corresponds to a particular permutation  $\rho$  of  $\{1, 2, \dots, n\}$ , and it suffices that for each particular permutation there is an input graph so that the only optimal tour is  $\rho$ .

Actually, due to the nature of the TSP, every tour is equivalent to  $n - 1$  other tours. This means that we in fact only need  $(n - 1)!$  different branches (each branch corresponds to the selection of a cycle of length  $n$ ). Now for each  $i, j$  so that  $i$  and  $j$  are adjacent on the cycle, define the costs  $c(i, j) := 1$  and  $c(j, i) := 1$ . All other costs are defined as  $c(i, j) := 2$ . It is clear that for this particular TSP instance, only the TSP tour (=cycle) which is formed by the 1-cost edges is optimal, and all other TSP tours are sub-optimal. Hence any correct TSP algorithm must have at least  $(n - 1)!$  different leaves.

To improve the argument, note there is a crucial difference between the input to the sorting problem and the input to the TSP problem in that the TSP problem requires  $\binom{n}{2}$  different edge costs (so it is order  $\Theta(n^2)$ , as opposed to an input of size  $n$  for the sorting problem). Now consider as possible TSP inputs all possible graphs with a cost function so that exactly one edge has cost 1 and all other edges have cost 2. This means that in order to find the minimum TSP tour, the TSP algorithm has to identify the 1-cost edge, which clearly requires scanning through all edges, so we get a lower bound of  $\Omega(\binom{n}{2}) = \Omega(n^2)$ .  $\square$

**Question** (Exercise Sheet 1 Question 3). *Consider the language UNARY-PRIME in the one letter alphabet  $\{a\}$  defined by  $\text{UNARY-PRIME} = \{a^n \mid n \text{ is prime}\}$ . Show that this language is in  $P$ .*

*Answer.* We can simply check whether any of the numbers  $2, \dots, n - 1$  divides  $n$ . The school division algorithm can be implemented in  $\mathcal{O}(n^2)$  time. Hence, the entire check can be done in  $\mathcal{O}(n^3)$  time, which is polynomial in the input size  $n$ .

**Note 1:** We can improve the running time to  $\mathcal{O}(\sqrt{n} \cdot \text{polylog}(n))$ , by checking divisors  $2, \dots, \lfloor \sqrt{n} \rfloor$  (we don't need to check larger values) and using an efficient  $\mathcal{O}(\log n(\log \log n))$  time for division.

**Note 2:** We can even use one of the polynomial time algorithms for the binary prime problem (which is in  $P$ ) to get an even better time complexity.  $\square$

**Question** (Exercise Sheet 1 Question 4). *Suppose  $S \subseteq \mathbb{N}$  is a set of natural numbers and consider the language UNARY- $S$  in the one letter alphabet  $\{a\}$  defined by  $\text{UNARY-}S = \{a^n \mid n \in S\}$ , and the language BINARY- $S$  in the two letter alphabet  $\{0, 1\}$  consisting of those strings*

starting with a 1 which are the binary representation of a number in  $S$ . Show that if UNARY- $S$  is in  $P$  then BINARY- $S$  is in  $\text{Time}(2^{cn})$  for some constant  $c$ .

*Answer.* We can convert a number with  $n$  bits from its binary representation to its unary representation by just appending  $a$ 's (at most  $2^{2n}$  of them) in  $\mathcal{O}(2^{2n})$  time. Since UNARY- $S$  is in  $P$ , for any input of length  $k$  we can determine if it is in the language in time  $\mathcal{O}(k^c)$  for some constant  $c > 0$ . Hence, we can determine if  $n \in \text{BINARY}S$  in time  $\mathcal{O}((2^{2n})^c) = \mathcal{O}(2^{2cn})$ .  $\square$

**Question** (Exercise Sheet 1 Question 5). We say that a propositional formula  $\phi$  is in 2-CNF if it is a conjunction of clauses, each of which contains exactly 2 literals. The point of this problem is to show that the satisfiability problem for formulas in 2-CNF can be solved by a polynomial time algorithm.

First note that any clause with 2 literals can be written as an implication in exactly two ways. For instance  $(p \vee \neg q)$  is equivalent to  $(q \rightarrow p)$  and  $(\neg p \rightarrow \neg q)$ , and  $(p \vee q)$  is equivalent to  $(\neg p \rightarrow q)$  and  $(\neg q \rightarrow p)$ .

For any formula  $\phi$ , define the directed graph  $G_\phi$  to be the graph whose set of vertices is the set of all literals that occur in  $\phi$ , and in which there is an edge from literal  $x$  to literal  $y$  if and only if, the implication  $(x \rightarrow y)$  is equivalent to one of the clauses in  $\phi$ .

- If  $\phi$  has  $n$  variables and  $m$  clauses, give an upper bound on the number of vertices and edges in  $G_\phi$
- Show that  $\phi$  is unsatisfiable if, and only if, there is a literal  $x$  such that there is a path in  $G_\phi$  from  $x$  to  $\neg x$  and a path from  $\neg x$  to  $x$ .
- Give an algorithm for verifying that a graph  $G_\phi$  satisfies the property stated in (b) above. What is the complexity of your algorithm?
- From (c) deduce that there is a polynomial time algorithm for testing whether or not a 2-CNF propositional formula is satisfiable.
- Why does this idea not work if we have 3 literals per clause?

*Proof.* (a) For each variable  $x$  we have two vertices  $x$  and  $\neg x$ . So there can be at most  $2n$  vertices. For each clause there can be at most two new edges added, hence a total of at most  $2m$ .

- ( $\Rightarrow$ ) If there is a path from  $x$  to  $\neg x$  ( $x \rightarrow p_1 \rightarrow \dots \rightarrow p_k \rightarrow \neg x$ ) and a path from  $\neg x$  to  $x$  ( $\neg x \rightarrow q_1 \rightarrow \dots \rightarrow q_k \rightarrow x$ ), then we will show that there is no satisfying assignment for  $x$ :
  - **Case 1** [ $x = \text{T}$ ]: Then by induction each of  $p_1, \dots, p_k, \neg x$  must be T and so  $x = \neg x$  which is a contradiction.
  - **Case 2** [ $x = \text{F}$ ]: Then by induction each of  $q_1, \dots, q_k, x$  must be T and so  $x = \neg x$  which is a contradiction.

( $\Leftarrow$ ) This direction is slightly more tricky. Assume that there is no path from  $x \rightarrow^* \neg x$  and  $\neg x \rightarrow^* x$  for any variable  $x$ . We will now construct a satisfying assignment for this graph.

We start with the claim that if there is a path  $p_1 \rightarrow \dots \rightarrow p_k$  in the graph, then there is also the path  $\neg p_k \rightarrow \dots \rightarrow \neg p_1$  (where double negation gives the original variable). This follows from the fact that when  $a \rightarrow b$  is present in the graph, then so is  $\neg b \rightarrow \neg a$ .

Consider the strongly connected components (SCC) of the graph, i.e., the equivalence classes formed by the bidirectional reachability relation. These form a directed acyclic graph with some of the components being potentially disconnected. We proceed for each unassigned variable and assign the truth value of the component to T (and automatically the truth value of the component of its negation to F).

We will now argue that this gives a valid truth assignment. To show this we need that there is no path  $y \rightarrow^* x$  and  $y \rightarrow^* \neg x$ , i.e., that  $x$  and  $\neg x$  cannot be in the same component. This follows from the above observation since a path from  $y \rightarrow^* x$  would also imply a path from  $\neg x \rightarrow^* y$ , and so a path from  $x \rightarrow^* \neg x$ , which by assumption does not exist.

- (c) A simple algorithm for performing this check is to start a BFS or DFS from each vertex  $x$  and check if we can reach  $\neg x$ . This requires  $\mathcal{O}(n \cdot (n + m))$  time. An  $\mathcal{O}(n + m)$  time algorithm can be obtained by computing the SCCs in  $\mathcal{O}(n + m)$  time and checking if any variable  $x$  is in the same component as its negation.
- (d) Both of the above algorithms run in time polynomial to the size of the input.
- (e) The above idea does not work because if we know that  $x$  is F in the clause  $(x \vee y \vee z)$ , then we cannot deduce anything about  $y$  and  $z$  individually.

□

**Question** (Exercise Sheet 1 Question 7). We define the complexity class of quasi-polynomial-time problems Quasi-P by:

$$\text{Quasi-P} = \bigcup_{k=1}^{\infty} \text{Time}(n^{(\log n)^k}).$$

Show that if  $L_1 \leq_P L_2$  and  $L_2 \in \text{Quasi-P}$ , then  $L_1 \in \text{Quasi-P}$ .

*Answer.* We need to design a Turing Machine  $M_1$  such that  $L(M_1) = L_1$ , and every accepting computation is in quasi-polynomial-time.

By assumption, there is a Turing Machine  $M_2$  with  $L(M_2) = L_2$ , and for every  $x \in L_2$ , the accepting computation finishes in time  $O(n^{(\log n)^{k_2}})$  for some constant  $k_2 \geq 1$ . Also there is a polynomial-time computable function  $f : \Sigma_1^* \rightarrow \Sigma_2^*$  such that  $x \in L_1$  if and only if  $f(x) \in L_2$ .

Given  $x \in \Sigma_1^*$ , the Turing Machine  $M_1$  first computes  $f(x)$ . Then it inputs  $f(x)$  to the Turing Machine  $M_2$ . If  $M_2$  accepts it, then  $M_1$  accepts. Otherwise,  $M_1$  rejects (or runs forever). We need to prove that  $L(M_2) = L_2$  and for every accepting configuration,  $M_2$  finishes in time  $O(n^{(\log n)^k})$ .

Let  $L_1 \subseteq \Sigma_1^*$  and  $x \in \Sigma_1^*$  be of length  $n$ . First, assume  $x \in L_1$ . Then  $f(x) \in L_2$  and by definition of  $M_2$ ,  $M_2(f(x))$  accepts. Furthermore, the length of  $f(x)$  is  $O(n^c)$  for some constant  $c > 0$ . Hence  $M_2$  will finish the computation in time

$$O((n^c)^{(\log n^c)^{k_2}}) = O(n^{c \cdot c^{k_2} \cdot (\log n)^{k_2}}) \leq O(n^{\log n \cdot (\log n)^{k_2}}) = O(n^{(\log n)^{k_2+1}}).$$

Hence the total time for  $M_1$  is

$$n^d + O(n^{(\log n)^{k_2+1}}) = O(n^{(\log n)^{k_2+1}}),$$

where  $O(n^d)$  for some constant  $d \geq 1$  is the time used to compute the function  $f$ .

Next assume  $x \notin L_1$ . Then  $f(x) \notin L_2$ , and  $M_2(f(x))$  does not accept (i.e., rejects or runs forever). This proves that  $L(M_2) = L_2$ , and also that every accepting computation is in quasi-polynomial time. Therefore,  $L_1 \in \text{Quasi-P}$ . □

**Question** (Exercise Sheet 1 Question 8). In general  $k$ -colourability is the problem of deciding, given a graph  $G = (V, E)$ , whether there is a colouring  $\chi : V \rightarrow \{1, \dots, k\}$  of the vertices such that if  $\{u, v\} \in E$ , then  $\chi(u) \neq \chi(v)$ . That is, adjacent vertices do not have the same colour.

1. Show that there is a polynomial time algorithm for solving 2-colourability.
2. Show that, for each  $k$ ,  $k$ -colourability is reducible to  $(k + 1)$ -colourability. What can you conclude from this about the complexity of 4-colourability?

*Answer.* First recall that as explained on page 29 of the notes,  $k$  is fixed and not part of the input.

1. A polynomial-time algorithm for 2-colourability can be designed based on, e.g., BFS and colouring each vertex that is explored from the current vertex alternately. (Details and a formal proof are omitted here, but a formal correctness proof would need to exploit that a graph is 2-colourable if and only if the graph is bipartite (which is equivalent to having no cycles of odd length).
2. Given any graph  $G = (V, E)$ , we need to give a polynomial-time<sup>1</sup> construction of another graph  $G'$  (depending on  $G$ ) such that  $G$  is  $k$ -colourable if and only if  $G'$  is  $(k+1)$ -colourable. To this end, let  $G = (V, E)$  be given. Construct  $G' = (V', E')$  by adding a single vertex  $z$ , i.e.,  $V' = V \cup \{z\}$ . With regards to the edges, keep all edges in  $G$  and additionally connect  $z$  to all other vertices, i.e.,  $E' = E \cup \{\{z, u\} : z \in V\}$  (see Figure 1 for an illustration).

First, we note that it is clear that the construction of  $G'$  can be done in time polynomial in the size of the input (which is the representation of the graph  $G$ ). Secondly, we will prove the equivalence. First assume  $G$  is  $k$ -colourable. Then, by colouring  $z$  with an extra colour, we obtain a colouring of  $G'$  with  $k + 1$  colours. For the other direction, assume  $G'$  is  $(k + 1)$ -colourable. Then, since  $z$  is connected to all other vertices, its colour must be unique. Hence for the set  $V' \setminus \{z\} = V$  only  $k$  colours are used, and since the colouring is valid for  $G'$ , it follows that the same colouring also works for  $V$ , proving that  $G$  is  $k$ -colourable.

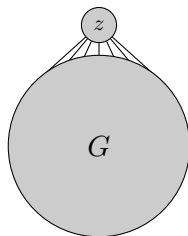


Figure 1: Illustration of the construction of  $G'$ .

Regarding the additional question about the complexity of 4-colourability, it was shown in the lectures that 3-colourability is NP-complete (which means it is NP-hard, i.e., any problem in NP can be reduced to it, and additionally, it is also in NP). By the polynomial-time reduction above, we can reduce every problem in NP first to 3-colourability, and then to 4-colourability. This proves that 4-colourability is NP-hard. It is also easy to see that 4-colourability is in NP (for example, simply guess non-deterministically a 4-colouring).

□

---

<sup>1</sup>The question did not explicitly ask for a polynomial time reduction, but this is needed for our conclusion about the complexity of 4-colourability.